

# Metrics of graph Laplacian eigenvectors

*Haotian Li & Naoki Saito*

Department of Mathematics  
University of California, Davis

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# Outline

- 1 Motivations
- 2 Basics of Graph Theory: Graph Laplacians
- 3 A Brief Review of Existed Metrics
- 4 Our Proposed Metrics
  - Time-Stepping Diffusion (TSD) Metric
  - Difference of Absolute Gradient (DAG) Pseudometric
- 5 Numerical Experiments
  - 2D Lattice  $P_{11} \times P_5$
  - Dendritic Tree of an RGC of a Mouse
- 6 Discussion & References

# Acknowledgment

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- Support from Julia community who helped our computational and graphical issues

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# Motivations: Problematic Ordering

- Key of building 1D wavelets by the Littlewood-Paley theory is based on *the ordering of Fourier modes*.
- Using *graph Laplacian eigenvectors* as “cosines” or Fourier modes on graphs with eigenvalues as (the square of) their “frequencies” has been popular.
- **Spectral Graph Wavelet Transform (SGWT)** of Hammond et al. derived wavelets on a graph based on the Littlewood-Paley theory that *organized the graph Laplacian eigenvectors corresponding to dyadic partitions of eigenvalues* by viewing the eigenvalues as “frequencies”.
- This view may face difficulty for graphs more complicated than very simple undirected unweighted paths and cycles.

# Motivations: Natural Ordering

- Therefore, we design “metrics” of graph Laplacian eigenvectors to detect the *“behavioral differences”* between them so that we can order the eigenvectors more naturally than using the size of the corresponding eigenvalues.
- Goal: Define proper “metrics” between the eigenvectors such that similar behavior ones are close and distinct behavior ones are far apart.
- The usual  $\ell^2$ -distance doesn't work since  $\|\phi_i - \phi_j\|_2 = \sqrt{2}\delta_{ij}$ .
- Furthermore, these metrics *help us design smooth multiscale basis dictionaries* that are quite important for many applications, e.g., efficiently approximating graph signals and solving differential equations on graphs.

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## Facts about Graph Laplacian $L(G)$

- Connected undirected graph  $G = (V, E, W)$ , with  $|V| = n$  and  $|E| = m$ .
- Graph Laplacian is given by  $L(G) = D(G) - W(G)$ , in which  $W(G)$  is the weights matrix of  $G$  and  $D(G)_{ii} = \sum_j W(G)_{ij}$ .
- $L(G)$  is a real symmetric positive semi-definite matrix, so the eigenvalues of  $L$  (i.e.,  $L(G)$ ) are *nonnegative* and the eigenvectors  $\{\phi_l\}_{l=0}^{n-1}$  form *an orthonormal basis*.

$$L\phi_l = \lambda_l\phi_l, \quad 0 = \lambda_0 < \lambda_1 \leq \dots \leq \lambda_{n-1}$$

- $\lambda_0 = 0$  is always an eigenvalue of  $L$  and its corresponding eigenvector  $\phi_0$  is a constant vector called *the DC component* (vector).
- The eigenvector  $\phi_1$  (with the first nonzero eigenvalue) is called *the Fiedler vector* which plays an important role in graph partitioning.
- Also,  $\{\phi_l\}_{l=0}^{n-1}$  and  $\{\lambda_l\}_{l=0}^{n-1}$  commonly viewed as the Fourier modes on graphs and the corresponding “frequencies”.



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# Review: Ramified Optimal Transportation (ROT) Metric

- First, by taking elementwise square, we convert each eigenvector to a probability mass function (pmf)  $\phi_i^2$  on the input *undirected* graph  $G = (V, E, W)$  with  $|V| = n$  and  $|E| = m$ .
- Define the ROT metric between a pair of the eigenvectors *by the minimal cost to move the probability mass from one pmf  $\phi_i^2$  to the other pmf  $\phi_j^2$ .*
- To do so, we first orient the edges in  $E(G)$  in an arbitrary manner to form a directed graph  $\tilde{G}$  and compute its incidence matrix  $Q := [\mathbf{q}_1 | \mathbf{q}_2 | \cdots | \mathbf{q}_m] \in \mathbb{R}^{n \times m}$ . Here,  $\mathbf{q}_k$  represents the endpoints of  $e_k$  : if  $e_k$  connect from vertex  $i$  to vertex  $j$ , then

$$q_k[l] = \begin{cases} -1 & \text{if } l = i; \\ 1 & \text{if } l = j; \\ 0 & \text{otherwise.} \end{cases}$$

## Review: ROT Metric Proposed by Saito (2018)

- For undirected graph  $G$ , we form *bidirected* graph  $\tilde{G}$  with  $\tilde{Q} = [Q | -Q]$ .
- Given  $\tilde{Q}$ , we solve the *balance equation* (underdetermined),

$$\tilde{Q}\mathbf{w} = \boldsymbol{\phi}_j^2 - \boldsymbol{\phi}_i^2, \quad \mathbf{w} \in \mathbb{R}_{\geq 0}^{2m}, \quad (1)$$

- Note that any  $\mathbf{w}$  satisfying Eq. (1) represents a transportation path (or plan) from  $\boldsymbol{\phi}_i^2$  to  $\boldsymbol{\phi}_j^2$ , and there may be multiple solutions.
- Define the cost of a transport path  $P \in \text{Path}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2)$  as:

$$\mathbf{M}_\alpha(P) := \sum_{e \in E(P)} w(e)^\alpha \text{length}(e), \quad \alpha \in [0, 1].$$

- Then, define *ROT metric* between  $\boldsymbol{\phi}_i$  and  $\boldsymbol{\phi}_j$  as:

$$d_{\text{ROT}}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2; \alpha) := \min_{P \in \text{Path}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2)} \mathbf{M}_\alpha(P).$$

- For  $\alpha = 1$ ,  $\min_P \mathbf{M}_1(P)$  becomes the optimal transport cost.

# Review: Hadamard (HAD) Product Affinity Measure Proposed by Cloninger and Steinerberger (2018)

- On a compact Riemannian manifold  $(\mathcal{M}, g)$ , the *HAD affinity measure* between eigenfunctions is defined as:

$$a_{\text{HAD}}(\phi_i, \phi_j)^2 := \|\phi_i \phi_j\|_2^{-2} \int_{\mathcal{M}} \left( \int_{\mathcal{M}} p(t, x, y) (\phi_i(y) - \phi_i(x)) (\phi_j(y) - \phi_j(x)) dy \right)^2 dx$$

$$= \frac{\|e^{t\Delta}(\phi_i \phi_j)\|_{L^2}^2}{\|\phi_i \phi_j\|_{L^2}^2}$$

where  $(\lambda_i, \phi_i)_i$  is an eigenpair of the Laplace-Beltrami operator  $\Delta$  on  $\mathcal{M}$ ,  $p(t, x, y)$  is the classical heat kernel, and the value of  $t$  should satisfy  $e^{-t\lambda_i} + e^{-t\lambda_j} = 1$ .

- It can be interpreted as *a global average of local correlation* between these two eigenfunctions.

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# Time-Stepping Diffusion (TSD) Metric

- The purpose of TSD metric is to design an optimal transport-like metric that *depends on time*. In other words, at each given time, we have a cost scheme (or metric).
- Given a time  $T$ , we consider the heat diffusion process on the graph. We want to measure *the cost of “flatten” the initial graph signal via diffusion process up to the time  $T$* .
- We expect the graph signal will be flatten out by this process and *the final cost ,as  $T \rightarrow \infty$ , behave similar with the  $d_{\text{ROT}}(\alpha = 1)$* .
- Notations: Denote the factorization of graph Laplacian matrix as  $L = \Phi\Lambda\Phi^T$ , in which  $\Phi = [\phi_0|\phi_1|\cdots|\phi_{n-1}]$  and  $\Lambda = \text{diag}([\lambda_0, \lambda_1, \cdots, \lambda_{n-1}])$ ; the incidence matrix as  $Q \in \mathbb{R}^{n \times m}$ , which is treated as the graph gradient, i.e.,  $Q^T = \nabla_G$ .

## TSD Cost Functional $K$ :

**(Heat diffusion)** Given initial  $\mathbf{f}_0$ , the governing ODE system which describes the graph signal  $\mathbf{u}(t)$ 's ( $\in \mathbb{R}^n$ ) evolution is following:

$$\frac{d}{dt}\mathbf{u}(t) + L \cdot \mathbf{u}(t) = \mathbf{0} \quad t \geq 0, \quad \mathbf{u}(0) = \mathbf{f}_0 \in \mathbb{R}^n$$

Since  $\{\boldsymbol{\phi}_0, \dots, \boldsymbol{\phi}_{n-1}\}$  forms an ONB of  $\mathbb{R}^n$ , we can get the general solution:

$$\mathbf{u}(t) = \sum_{k=0}^{n-1} \langle \mathbf{f}_0, \boldsymbol{\phi}_k \rangle e^{-\lambda_k t} \boldsymbol{\phi}_k$$

At a certain time  $T$ , we define the following *TSD cost functional*:

$$K(\mathbf{f}_0, T) := \int_0^T \|\nabla_G \mathbf{u}(t)\|_1 dt \quad \nabla_G \text{ is the graph gradient.}$$

which can be interpreted as *accumulated total variation* of  $\mathbf{u}(t)$ .



# Convergence of TSD Cost and TSD Metric

- We can show that  $\lim_{T \rightarrow \infty} K(\mathbf{f}_0, T) < \infty$  for any  $\mathbf{f}_0 \in \mathbb{R}^n$ .
- After setting the input signal  $\mathbf{f}_0 = \boldsymbol{\phi}_i - \boldsymbol{\phi}_j$ , we define the *TSD metric between the eigenvectors at time  $T$*  by

$$d_{\text{TSD}}(\boldsymbol{\phi}_i, \boldsymbol{\phi}_j; T) := K(\mathbf{f}_0, T)$$

- Furthermore, we can show that for any  $T > 0$  (including  $T = \infty$ ),  $K(\cdot, T)$  is a norm on  $\mathcal{L}_0^2(V) := \{\mathbf{f} \in \mathcal{L}^2(V) \mid \sum_{x \in V} \mathbf{f}(x) = 0\}$ .
- Cost Conjecture: As  $T \rightarrow \infty$ , we expect

$$d_{\text{ROT}}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2; \alpha = 1) \leq d_{\text{TSD}}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2; T = \infty) \leq C(G) \cdot d_{\text{ROT}}(\boldsymbol{\phi}_i^2, \boldsymbol{\phi}_j^2; \alpha = 1)$$

where  $C(G)$  is a constant depending on the graph  $G$ .

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## Difference of Absolute Gradient (DAG) Pseudometric

- The idea of DAG is that we use the absolute gradient of each eigenvector as its feature vector describing its behavior.
- We define *DAG pseudometric* as:

$$d_{\text{DAG}}(\boldsymbol{\phi}_i, \boldsymbol{\phi}_j) := \|\ |\nabla_G|\boldsymbol{\phi}_i - |\nabla_G|\boldsymbol{\phi}_j \|_2 = \|\text{abs.}(Q^T \boldsymbol{\phi}_i) - \text{abs.}(Q^T \boldsymbol{\phi}_j)\|_2$$

- Further, we derive the following equations:

$$\begin{aligned} d_{\text{DAG}}(\boldsymbol{\phi}_i, \boldsymbol{\phi}_j)^2 &= \langle |\nabla_G|\boldsymbol{\phi}_i - |\nabla_G|\boldsymbol{\phi}_j, |\nabla_G|\boldsymbol{\phi}_i - |\nabla_G|\boldsymbol{\phi}_j \rangle_E \\ &= \langle |\nabla_G|\boldsymbol{\phi}_i, |\nabla_G|\boldsymbol{\phi}_i \rangle_E + \langle |\nabla_G|\boldsymbol{\phi}_j, |\nabla_G|\boldsymbol{\phi}_j \rangle_E - 2\langle |\nabla_G|\boldsymbol{\phi}_i, |\nabla_G|\boldsymbol{\phi}_j \rangle_E \\ &= \lambda_i + \lambda_j - \sum_{x \in V} \sum_{y \sim x} |\boldsymbol{\phi}_i(x) - \boldsymbol{\phi}_i(y)| \cdot |\boldsymbol{\phi}_j(x) - \boldsymbol{\phi}_j(y)| \end{aligned}$$

in which  $\langle \cdot, \cdot \rangle_E$  is the inner product over edges.

- The last term of the formula can be viewed as *a global average of absolute local correlation* between eigenvectors, which is close to the interpretation of HAD affinity measure.
- Given the eigenvectors, *the computational cost is  $O(|E|)$ .*

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# Numerical Experiments

- To evaluate the performance of those “metrics” for a given graph, we assemble the *distance matrix* by the mutual behavioral difference between the eigenvectors (or corresponding pmfs, e.g.,  $\phi_i^2$  for  $d_{\text{ROT}}$ ) using each “metric”.
- Then use the *classical MDS (Multidimensional Scaling)* on the distance matrix and embed the eigenvectors into the low dimensional Euclidean space, i.e.,  $\mathbb{R}^2$  or  $\mathbb{R}^3$ .
- By doing so, we can get the *visual arrangement* of eigenvectors organized by the corresponding “metric”.

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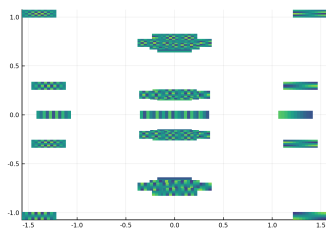
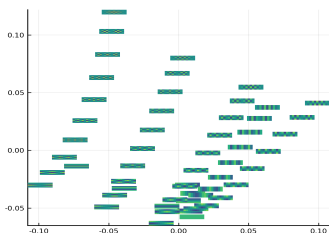
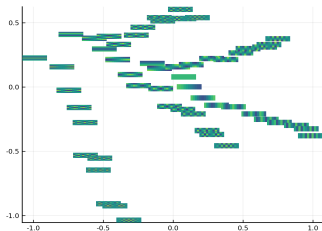
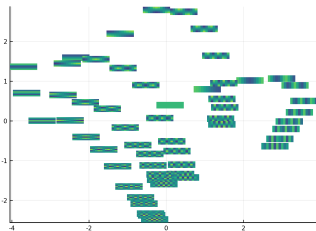
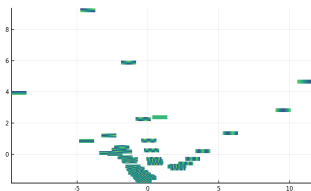
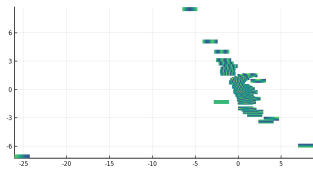
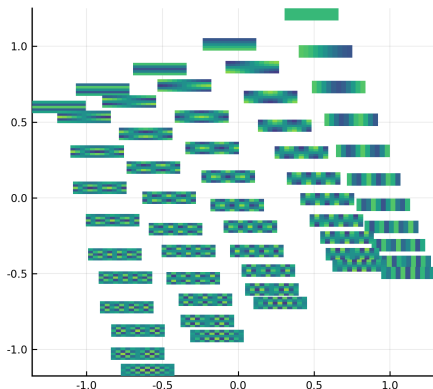
2D Lattice  $P_{11} \times P_5$ :  $d_{\text{ROT}}$  and  $a_{\text{HAD}}$ (a)  $d_{\text{ROT}}(\phi_i^2, \phi_j^2; \alpha = 1)$ (b)  $a_{\text{HAD}}(\phi_i, \phi_j)$ 

Figure: 2D-MDS embedding of the eigenvectors of  $11 \times 5$  unweighted lattice graph based on the ROT and the HAD metrics: each small heatmap plot describes how the eigenvector looks like on the lattice graph.

- They both reveal the *two-dimensional ordering* of the eigenvectors.
- $a_{\text{HAD}}$  is better but still has a little misordering in  $y$  (vertical) direction.

2D Lattice  $P_{11} \times P_5$ :  $d_{\text{TSD}}$  with different  $T$ (a)  $T = 0.1$ (b)  $T = 1$ (c)  $T = 10$ (d)  $T = \infty$



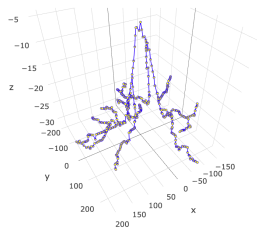
2D Lattice  $P_{11} \times P_5$ :  $d_{\text{DAG}}$ 

- $d_{\text{DAG}}$  nicely detect two directions of the oscillations. The eigenvectors are organized in *2D array*.
- For each column of the array, the eigenvectors have the same oscillation pattern in  $y$  direction and oscillation in  $x$  direction increases linearly. Vice versa.

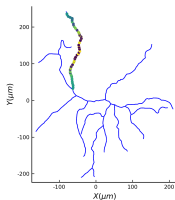
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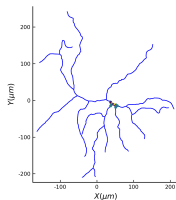
## RGC#100: Two Types of Eigenvectors



(a)

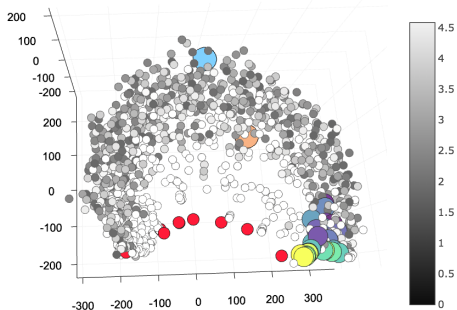


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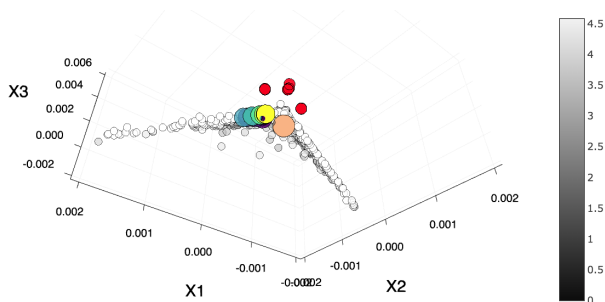


(c)

- (a): The 3D dendritic tree of RGC#100 graph.
- (b): The representative of eigenvectors with *semi-global oscillations* on the upper-left branch (projected in  $\mathbb{R}^2$ ).
- (c): The representative of eigenvectors with much more *localized active support* around junctions/bifurcation vertices (projected in  $\mathbb{R}^2$ ).
- The eigenvalues of two types eigenvectors can *be very close at 4.0*.

RGC#100:  $d_{\text{ROT}}$  with  $\alpha = 0.5$ 

**Figure:** 3D-MDS embedding of the Laplacian eigenvectors of unweighted RGC #100 graph based on  $d_{\text{ROT}}(\phi_i^2, \phi_j^2; \alpha = 0.5)$ : The large blue circle = the DC component and the big orange circle = the Fiedler vector; the small red circles = localized eigenvectors; the medium viridis circles = the semi-global oscillation eigenvectors. Grey scales represent the magnitude of the eigenvalues.

RGC#100:  $a_{\text{HAD}}$ 

- $a_{\text{HAD}}$  successfully separates the two types of eigenvectors, but everything is *too closely located*.
- The reason is that the Hadamard product will almost vanish on graphs, i.e.,  $\phi_i \circ \phi_j \approx \mathbf{0} \in \mathbb{R}^n$ , if the active support of the concentrated part of  $\phi_i$  and  $\phi_j$  do not overlap.

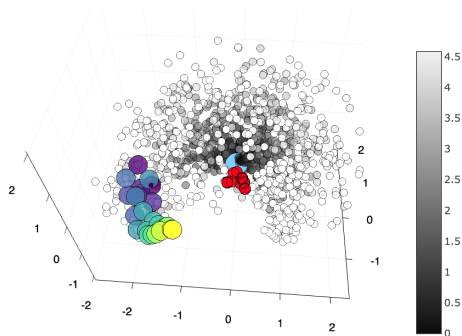
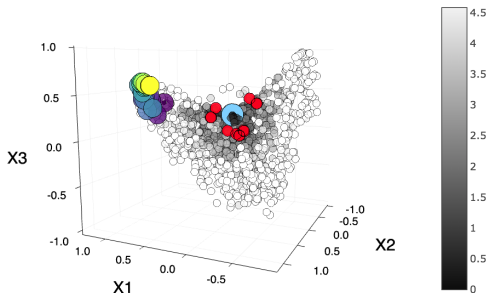
RGC#100:  $d_{\text{TSD}}$  with  $T = 0.1$ 

Figure: 3D-MDS embedding of the Laplacian eigenvectors of unweighted RGC #100 graph based on  $d_{\text{TSD}}(\phi_i, \phi_j; T = 0.1)$ .

RGC#100:  $d_{\text{DAG}}$ 

- The 3D-MDS result of  $d_{\text{TSD}}(\phi_i, \phi_j; T = 0.1)$  and  $d_{\text{DAG}}(\phi_i, \phi_j)$  have similar structures.
- They also *successfully split* the two types of eigenvectors.
- But the DC vector and the Fiedler vector are *too close to distinguish* from each other in the two results.

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# Discussion

- In general, we are interested in two types of eigenvector behavior patterns on graphs: *global and directional oscillation pattern* and *energy concentration pattern*.
- Global and directional oscillation pattern represents *how the eigenvector globally oscillate on the graphs*, e.g., the DCT type II eigenvectors on 1D path graphs where the oscillation pattern is completely characterized by the eigenvalues; the eigenvectors of 2D lattice graphs or more general Cartesian product graphs where the oscillation patterns can be characterized by different directions.
- The energy concentration pattern of the eigenvector describes *which part of the graphs that the eigenvector is more active*, e.g., the tree graphs where eigenvectors may concentrated on the junctions or may have semi-global oscillation structure on certain branches.

# Discussion

- Empirically, the DAG pseudometric and the HAD affinity measure reveal the directional oscillation patterns of the eigenvectors quite well.
- The ROT metric works well on energy concentration detection.
- The TSD time-dependent metric behaves similar to DAG with small  $T$  and similar to ROT with large  $T$ .
- However, the huge computational cost of TSD with large  $T$  limit its performance on complicated graphs.
- In the future, we will work on designing better *auto-adaptive* and *cost efficient* “metrics” which expected to be *good for both types* of eigenvector behaviors on different graphs.

## Simplified ROT (sROT) Metric

- If the underlying graph  $G$  is a *tree* (connected graph without loop), we can develop a computational efficient simplified ROT (sROT) metric.
- Notice that there are only two types of vertices in a tree: branch vertices (degree less than 2) and junction vertices (degree greater than 2).
- Therefore, one can simplified the tree graph *by treating the branch nodes on the same branch as one vertex* and get a simplified graph  $G_s$ .
- Correspondingly, instead of converting the eigenvectors  $\phi_i$  into pmfs  $\phi_i^2$  on  $G$ , we can convert them into *low-dimensional* pmfs  $\theta_i$  on  $G_s$  by integrating the values of  $\phi_i^2$  over each branch of the tree.
- Define *sROT metric* as:

$$d_{\text{sROT}}(\phi_i^2, \phi_j^2; \alpha) := d_{\text{ROT}}(\theta_i, \theta_j; \alpha)$$

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**Thanks for your attention!**  
**Any questions?**